TF-Ranking: Scalable TensorFlow Library for Learning-to-Rank

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1 INTRODUCTION

With the high potential of deep learning for real-world data-intensive applications, a number of open source packages have emerged in recent years and are under active development, including TensorFlow [1], PyTorch [34], Caffe [21], and MXNet [10]. Supervised learning is one of the main use cases of deep learning packages. However, compared with the comprehensive support for classification or regression in open-source deep learning packages, there is a paucity of support for ranking problems.

A ranking problem is defined as a derivation of ordering over a list of items that maximizes the utility of the entire list. It is widely applicable in several domains, such as Information Retrieval and Natural Language Processing. Some important practical applications include web search, recommender systems, machine translation, document summarization, and question answering [28].

In general, a ranking problem is different from classification or regression tasks. While the goal of classification or regression is to predict a label or a value for each individual item as accurately as possible, the goal of ranking is to optimally sort the entire item list such that, for some notion of relevance, the items of highest relevance are presented first. To be precise, in a ranking problem, we are more concerned with the relative order of the relevance of items than their absolute magnitudes.

That ranking is a fundamentally different problem entails that classification or regression metrics and methodologies do not transfer effectively to the ranking domain. To fill this void, a number of metrics and a class of methodologies that are inspired by the challenges in ranking have been proposed in the literature. For example, widely-utilized metrics such as Normalized Discounted Cumulative Gain (NDCG) [20], Expected Reciprocal Rank (ERR) [8], Mean Reciprocal Rank (MRR) [14], Mean Average Precision (MAP), and Average Relevance Position (ARP) [48] are designed to emphasize the items that are ranked higher in the list.

Similarly, a class of supervised machine learning techniques that attempt to solve ranking problems—referred to as learning-to-rank [28]—has emerged in recent years. Broadly, the goal of learning-to-rank is to learn from labeled data a parameterized function that maps feature vectors to real-valued scores. During inference, this scoring function is used to sort and rank items.

Most learning-to-rank methods differ primarily in how they define surrogate loss functions over ranked lists of items during training to optimize a non-differentiable ranking metric, and by that measure fall into one of pointwise, pairwise, or listwise classes of algorithms. Pointwise methods [13, 17, 18] approximate ranking to a classification or regression problem and as such attempt to optimize the discrepancy between individual ground-truth labels and the absolute magnitude of relevance scores produced by the learning-to-rank model. On the other hand, pairwise [5, 22] or listwise [7, 42, 43]
methods either model the pairwise preferences or define a loss over entire ranked list. Therefore, pairwise and listwise methods are more closely aligned with the ranking task [28].

There are other factors that distinguish ranking from other machine learning paradigms. As an example, one of the challenges facing learning-to-rank is the inherent biases [24, 46] that exist in labeled data collected through implicit feedback (e.g., click logs). Recent work on unbiased learning-to-rank [2, 25, 41] explores ways to counter position bias [24] in training data and produce a consistent and unbiased ranking function. These techniques work well with pairwise or listwise losses, but not with pointwise losses [41].

From the discussion above, it is clear that a library that supports the learning-to-rank problem has its own unique set of requirements and must offer a functionality that is specific to ranking. Indeed, a number of open source packages such as RankLib2 and LightGBM [26] exist to address the ranking challenge.

Existing learning-to-rank libraries, however, have a number of important drawbacks. First, they were developed for small data sets (thousands of queries) and do not scale well to massive click logs (hundreds of millions of queries) that are common in industrial applications. Second, they have very limited support for sparse features and can only handle categorical features with a small vocabulary. Crucially, extensive feature engineering is required to handle textual features. In contrast, deep learning packages like TensorFlow can effectively handle sparse features through embeddings [30]. Finally, existing learning-to-rank libraries do not support the recent advances in unbiased learning-to-rank.

To address this gap, we present our experiences in building a scalable, comprehensive, and configurable industry-grade learning-to-rank library in TensorFlow. Our main contributions are:

- We propose an open-source library for training large scale learning-to-rank models using deep learning in TensorFlow.
- The library is flexible and highly configurable: it provides an easy-to-use API to support different scoring mechanisms, loss functions, example weights, and evaluation metrics.
- The library provides support for unbiased learning-to-rank by incorporating inverse propensity weights in losses and metrics.
- We demonstrate the effectiveness of our library by experiments on two large-scale search and recommendation applications, especially when employing listwise losses and sparse textual features.
- We demonstrate the robustness of our library in a large-scale distributed training setting.

Our current implementation of the TensorFlow Ranking library is by no means exhaustive. We envision that this library will provide a convenient open platform for hosting and advancing state-of-the-art ranking models based on deep learning techniques, and thus facilitate both academic research as well as industrial applications.

The remainder of this paper is organized as follows. Section 2 formulates the problem of learning to rank and provides an overview of existing approaches. In Section 3, we present an overview of the proposed learning-to-rank platform, and in Section 4 we present the implementation details of our proposed library. Section 5 showcases uses of the library in a production environment and demonstrates experimental results. Finally, Section 6 concludes this paper.

2 LEARNING-TO-RANK

In this section, we provide a high-level overview of learning-to-rank techniques. We begin by presenting a formal definition of learning-to-rank and setting up notation.

2.1 Setup

Let \( X \) denote the universe of items and let \( x \in X^n \) represent a list of \( n \) items and \( x_i \in x \) an item in that list. Further denote the universe of all permutations of size \( n \) by \( \Pi^n \), where \( \pi \in \Pi^n \) is a bijection from \([1 : n]\) to itself. \( \pi \) may be understood as a total ranking of items in a list where \( \pi(i) \) yields the rank according to \( \pi \) of the \( i^{\text{th}} \) item in the list and \( \pi^{-1}(r) \) yields the index of the item at rank \( r \), and we have that \( \pi^{-1}(\pi(i)) = i \). A ranking function \( f : X^n \rightarrow \Pi^n \) is a function that, given a list of \( n \) items, produces a permutation or a ranking of that list.

The goal of learning-to-rank, in broad terms, is to learn a ranking function \( f \) from training data such that items as ordered by \( f \) yield maximal utility. Let us parse this statement and discuss each component in more depth.

2.2 Training Data

We begin with a description of training data. Learning-to-rank, which is an instance of supervised learning, assumes the existence of a ground-truth permutation \( \pi^* \) for a given list of items \( x \).

In most real-world settings, ground-truth is provided in its more general form: a set of permutations or in other words a partial ranking. In a partial ranking \( X_1 \succ X_2 \succ \ldots \succ X_k \), where \( X_i \)s are \( k \) disjoint subsets of elements of \( x \in X^n \) (\( k \leq n \)), items in \( X_i \) are preferred over those in \( X_i \succ i \), but within each \( X_i \) items may be permuted freely. When \( k = n \) partial ranking reduces to a total ranking.

As a concrete example, consider the task of ad hoc retrieval where given a (textual) query the ranking algorithm retrieves a relevant list of documents from a large corpus. When constructing a training dataset, one may recruit human experts to examine an often very small subset of candidate documents for a given query and grade the documents’ relevance with respect to that query on some scale (e.g., 0 for “not examined” or “not relevant” to 5 for “highly relevant”). A relevance grade for document \( x_i \) is considered its “label” \( y_i \). Similarly, in training datasets that are constructed by implicit user feedback such as click logs, documents are either relevant and clicked (\( y = 1 \)) or not (\( y = 0 \)). In either case, a list of labels \( y \) induces a partial ranking of documents.

In order to simplify notation throughout the remainder of this paper and without loss of generality, we assume the existence of \( \pi^* \), a correct total ranking. \( \pi^* \) can be understood as an ranking induced by a list of labels \( y \in \mathbb{R}^n \) for \( x \in X^n \). As such, our training data set of \( m \) items can be defined as \( S^m = \{(x, \pi^*) | x \in X^n, \pi^* \in \Pi^n \} \) or equivalently \( S^m = \{(x, y) | x \in X^n \times \mathbb{R}^n \} \).

Returning to the case of ad hoc retrieval, it is worth noting that each item \( x_i \in x \) is in fact a pair of query and document \( (q, d_1) \): It is generally the case that the pair \( (q, d_1) \) is transformed to a feature vector \( x_i \).

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2Available at: https://sourceforge.net/p/lemur/wiki/RankLib/
We now turn to the notion of utility. As noted in Section 1, the utility $y$ where
example, the mean reciprocal rank (MRR) is defined as:
\[
\text{mean of the above metrics is calculated and reported instead. For}
\]
its simplest form, the scoring function is univariate and can be decomposed into a per-item scoring function as shown in Equation 1, where $g : x \rightarrow \mathbb{R}$ maps a feature vector to a real-valued score.

\[
h(x) = [g(x_1), \forall 1 \leq i \leq n] = [g(x_1), g(x_2), \ldots, g(x_n)].
\]

The scoring function $h$ is typically parameterized by a set of parameters $\theta$ and can be written as $h(\cdot; \theta)$. Many parameterization options have been studied in the learning-to-rank literature including linear functions [23], boosted weak learners [45], gradient-boosted trees [6, 16], support vector machines [23, 25], and neural networks [5]. Our library offers deep neural networks as the basis including linear functions [23], boosted weak learners [45], gradient-

2.4 Utility and Ranking Metrics
We now turn to the notion of utility. As noted in Section 1, the utility of an ordered list of items is often measured by a number of standard ranking-specific metrics. What makes ranking metrics unique and suitable for this task is that, in ranking, it is often desirable to have ranking-specific metrics. What makes ranking metrics unique and suitable for this task is that, in ranking, it is often desirable to have fewer errors at higher ranked positions; this principle is reflected in many ranking metrics:

\[
\begin{align*}
\text{RR}(\pi, y) &= \frac{1}{\min_j \{y_{\pi^{-1}(j)} > 0\}}, \\
\text{RP}(\pi, y) &= \frac{\sum_{j=1}^{n} y_j \pi(j)}{\sum_{j=1}^{n} y_j}, \\
\text{DCG}(\pi, y) &= \sum_{j=1}^{n} \frac{2^{y_j} - 1}{\log_2(1 + \pi(j))}, \\
\text{NDCG}(\pi, y) &= \frac{\text{DCG}(\pi, y)}{\text{DCG}(\pi^*, y)},
\end{align*}
\]

where $y_j \in y$ are ground-truth labels that induce $\pi^*$, and $\pi(i)$ is the rank of the $i$th item in $x$. RR is the reciprocal rank of the first relevant item. RP is the positions of items weighted by their relevance values [48]. DCG is the Discounted Cumulative Gain [20], and NDCG is DCG normalized by the maximum DCG obtained from the ideal ranked list $\pi^*$.

Note that, given $m$ evaluation samples $(\pi_k, y_k), 1 \leq k \leq m$, the mean of the above metrics is calculated and reported instead. For example, the mean reciprocal rank (MRR) is defined as:

\[
\text{MRR} = \frac{1}{m} \sum_{k=1}^{N} \text{RR}(\pi_k, y_k).
\]

Our library supports commonly used ranking metrics and enables easy development and addition of arbitrary metrics.

2.5 Loss Functions
Learning-to-rank seeks to maximize a utility or equivalently minimize a cost or loss function. Assuming there exists a loss function $\ell(\cdot)$, the objective of learning-to-rank is to find a ranking function $f^*$ that minimizes the empirical loss over training samples:

\[
f^* = \arg\min_{f : \mathcal{X}^n \rightarrow \Omega^m} \frac{1}{m} \sum_{(x, y) \in \mathcal{S}^m} \ell(y, f(x)).
\]

Replacing $f$ with a scoring function $h$ as is often the case yields the following optimization problem:

\[
h^* = \arg\min_{h : \mathcal{X}^n \rightarrow \mathbb{R}^m} \frac{1}{m} \sum_{(x, y) \in \mathcal{S}^m} \ell(y, h(x)),
\]

where $\ell(\cdot)$ is a loss function equivalent to $\ell(\cdot)$ that acts on scores instead of permutations induced by scores.

This setup naturally prefers loss functions that are differentiable. Most ranking metrics, however, are either discontinuous or flat everywhere due to the use of the sort operation and as such cannot be directly optimized by learning-to-rank methods. With a few notable exceptions [29, 43], most learning-to-rank approaches therefore define and optimize a differentiable surrogate loss instead. They do so by, among other techniques, creating a smooth variant of popular ranking metrics [35, 39]; deriving tight upper-bounds on ranking metrics [42]; bypassing the requirement that a loss function be defined altogether [6]; or, otherwise designing losses that are loosely related to ranking metrics [7, 43].

Our library supports a number of surrogate loss functions. As an example of a pointwise loss, the sigmoid cross-entropy for binary relevance labels $y_j \in \{0, 1\}$ is computed as follows:

\[
\ell(y, \hat{y}) = -\sum_{j=1}^{n} y_j \log(p_j) + (1 - y_j) \log(1 - p_j)
\]

where $p_j = \frac{1}{1 + \exp(-y_j)} \hat{y} \pm h(x)$ are scores computed by the scoring function $h$. As an example of a pairwise loss in our library, the pairwise logistic loss is defined as:

\[
\hat{\ell}(y, \hat{y}) = \sum_{j=1}^{n} \sum_{k=1}^{n} I(y_j > y_k) \log(1 + \exp(\hat{y}_k - \hat{y}_j))
\]

where $I(\cdot)$ is the indicator function. Finally, as an example of a listwise loss [11], our library provides the implementation of Softmax Cross-Entropy, ListNet [7], and ListMLE [43] among others. For example, the Softmax Cross-Entropy loss is defined as follows:

\[
\hat{\ell}(y, \hat{y}) = -\sum_{j=1}^{n} y_j \log(\frac{\exp(\hat{y}_j)}{\sum_{j=1}^{n} \exp(\hat{y}_j)})
\]

2.6 Item Weighting
Finally, we conclude this section by a note on bias in learning-to-rank. As discussed in Section 1, a number of studies have shown that click logs exhibit various biases including position bias [24]. In short, users are less likely to examine and click items at larger
which, in turn, is treated as a vector of implicit features for subsequent neural network layers. For example, discrete elements such as words or characters from a finite vocabulary are transformed using an embedding matrix—also referred to as an embedding layer or embeddings [4]—which maps every element of the vocabulary to a learned, dense representation. This particular representation learning is useful for learning-to-rank over documents, web pages or other textual data.

Given these properties, neural networks are excellent candidates for modeling a score-and-sort approach to learning-to-rank. In particular, the scoring function \( h(.) \) in Equation 1 can be parameterized by a neural network. In such a setup, feature representations can be jointly learned with the parameters of \( h(.; \theta) \) while minimizing the objective \( \ell \) averaged over the training data. This is the general setup we adopt and implement in the TensorFlow Ranking library.

TensorFlow Ranking is built on top of TensorFlow, a popular open-source library for large scale training, evaluation and serving of machine learning and deep learning models. TensorFlow supports high performance tensor (multi-dimensional vector) manipulation and computation via what is referred to as “computational graphs.” A computational graph expresses the logic of a sequence of tensor manipulations, with each node in the graph corresponding to a single tensor operation (op). For example, a node in the computation graph may multiply an “input” tensor with a “weight” tensor, a subsequent node may add a “bias” tensor to that product, and a final node may pass the resultant tensor through the Sigmoid function.

The concept of a computation graph with tensor operations simplifies the implementation of the backpropagation [9] algorithm for training neural networks. In a forward pass, the values at each node are computed by composing a sequence of tensor operations, and in a backward pass, gradients are accumulated in the the reverse fashion. TensorFlow enables such propagation of gradients through automatic differentiation [1]: each operation in the computation graph is equipped with a gradient expression with respect to its input tensors. In this way, the gradient of a complex composition of tensor operations can be automatically inferred during a backward pass through the computation graph. This allows for composition of a large number of operations to construct deeper networks.

Another computationally attractive property of the TensorFlow framework is its support, via TensorFlow Estimator [12], of distributed training of neural networks. TensorFlow Estimator is an abstract library that takes a high-level training, evaluation, or prediction logic and hides the execution logic from developers. An Estimator object encapsulates two major abstract components that can be further customized: (1) input_fn, which reads in data from a persistent storage and creates tensors for features and labels, and (2) model_fn which processes input features and labels, and depending on the mode (TRAIN, EVAL, PREDICT), returns a loss value, evaluation metrics, or predictions. The computation graph expressed within the model_fn may depend on the mode. This is particularly useful for learning-to-rank because the model may need entire lists of items during training (to compute a listwise loss, for example), but during serving, it may score each item independently. The model function itself can be expressed as a combination of a logits builder and a Head abstraction, where the logits builder generates the values in the forward computation of the graph, and the Head object defines loss objectives and associated metrics.

These abstractions, along with modular design, the ability to distribute the training of a neural network and to serve on a variety of high-performance hardware platforms (CPU/GPU/TPUs) are what make the TensorFlow ecosystem a suitable platform for a neural network-based learning-to-rank library. In the next section, we discuss how the design principles in TensorFlow and the Estimator workflow inspire the design of the TensorFlow Ranking library.

4 COMPONENTS

Motivated by design patterns in TensorFlow and the Estimator framework, TensorFlow Ranking constructs computational subgraphs via callbacks for various aspects of a learning-to-rank model such as scoring function \( h(.) \), losses \( \ell(.) \), and evaluation metrics (see Section 2). These subgraphs are combined together in the
Estimator framework, via a custom callback to create a `model_fn`. The `model_fn` itself can be decomposed into a logits builder, which represents the output of the neural network layers, and a Head abstraction, which encapsulates loss and metrics. This decomposition is particularly suitable to learning-to-rank problems in the score-and-sort approach. The logits builder corresponds to the scoring function, defined in Section 2.3, and the Head corresponds to losses and metrics.

It is important to note that this decomposition also provides modularity and the ability to switch between various combinations of scoring functions and ranking heads. For example, as we show in the code examples below, switching between a pointwise or a listwise loss, or incorporating embedding for sparse features into the model can be expressed in a single line code change. We found this modularity to be valuable in practical applications, where rapid experimentation is often required.

The overall architecture of TensorFlow Ranking library is illustrated in Figure 1. The key components of the library are: (1) data reader, (2) transform function, (3) scoring function, (4) ranking loss functions, (5) evaluation metrics, (6) ranking head, and (7) a `model_fn` builder. In the remainder of this section, we will describe each component in detail.

### 4.1 Reading data using `input_fn`

The `input_fn`, as shown in Figure 1, reads in data either from a persistent storage or data generated by another process, to produce dense and sparse tensors of the appropriate type, along with the labels. The library provides support for several popular data formats (LIBSVM, `tf.SequenceExample`). Furthermore, it allows developers to define customized data readers.

Consider the case when the user would like to construct a custom `input_fn`. The user defines a parser for a batch of serialized datapoints that returns a feature dictionary containing 2-D and 3-D tensors. Given feature definitions, the transform function produces dense 2-D or 3-D tensors for context and per-item features respectively. The following code snippet shows how one may construct a custom `input_fn`.

```python

def _parse_single_datapoint(serialized):
    """User defined logic to parse a batch of serialized datapoints to a dictionary of 2-D and 3-D tensors."
    return features

def input_fn(file_pattern):
    """Generate features and labels from input data."
    dataset = tfr.data.build_ranking_dataset_with_parsing_fn(  
        file_pattern=file_pattern,  
        parsing_fn=_parse_single_datapoint,  
    )
    features = dataset.make_one_shot_iterator().get_next()
    label = tf.squeeze(features.pop(_LABEL_FEATURE), axis=2)
    return features, label
```

### 4.2 Feature Transformation with `transform_fn`

As discussed in Section 3, sparse features such as words or n-grams can be transformed to dense features using (learned) embeddings. More generally, any raw feature may require some form of transformation. Such transformations may be implemented in `transform_fn`, a function that is applied to the output of `input_fn`. The library provides standard functions to transform sparse features to dense features based on feature definitions. A feature definition in TensorFlow is a user-defined `tf.FeatureColumn` [12], an expression of the type and attributes of features. Given feature definitions, the transform function produces dense 2-D or 3-D tensors for context and per-item features respectively. The following code snippet demonstrates an implementation of the `transform_fn`. Context and per-item feature definitions are passed
to the encode_listwise_features function, which in turn returns
dense tensors for each of context and per-item features.

```python
def make_transform_fn():
    def _transform_fn(features, mode):
        context_feature_columns = ('unigrams': embedding_column('unigrams', dimension=10, vocab_list=_VOCAB_LIST))
        example_feature_columns = ('utility': numeric_column('utility', shape=(1), default_value=0.0, dtype=float32))
        context_features, example_features = tfr.feature.example_feature_columns
        return
```

### 4.3 Feature Interactions using scoring_fn

The library allows users to build arbitrary scoring functions defined in Section 2.3. A scoring function takes batched tensors in the form of 2-D context features and 3-D per-item features, and returns a score for a single item or a group of items. The scoring function is supplied to the model builder via a callback. The model uses the scoring function internally to generate scores during training and inference, as shown in Figure 1. The signature of the scoring function is shown below, where mode, params, and config are input arguments for model_fn that supply model hyperparameters and configuration for distributed training [12]. The code snippet below, constructs a 3-layer feedforward neural network with ReLUs [32].

```python
def _score_fn(context_features, group_features, mode, params, config):
    net = layers.dense(net, units=128, activation="relu")
    net = concat(layers.flatten(group_features.values()), layers.flatten(context_features.values()))
    for i in range(3):
        net = layers.dense(net, units=128, activation="relu")
    logits = layers.dense(cur_layer, units=1)
    return logits
```

### 4.4 Ranking Losses

Here, we describe the APIs for building loss functions defined in Section 2.5. Losses in TensorFlow are functions that take in inputs, labels, and a weight, and return a weighted loss value. The library has a pre-defined set of pointwise, pairwise and listwise ranking losses. The loss key is an enum over supported loss functions. These losses can be instantiated using a factory function that takes a metric key and a weights tensor, and returns a metric function compatible with Estimator. The metric function itself takes in predictions, labels, and weights to compute a scalar measure. The metric key is an enum over supported metric functions, described in Section 2.4. During evaluation, the library supports computing both weighted and unweighted metrics, for example weights defined in Section 2.6, which facilitates evaluation in the context of unbiased learning-to-rank. The code snippet below shows how to build metric function.

```python
def _train_op_fn(loss):
    return tf.contrib.layers.optimize_loss(
        loss=loss,
        global_step=tf.train.get_global_step(),
        learning_rate=params.learning_rate,
        optimizer="Adagrad")
```

### 4.5 Ranking Metrics

The library provides an API to compute most common ranking metrics defined in Section 2.4. Similar to loss functions, a metric can be instantiated using a factory function that takes a metric key and a weights tensor, and returns a metric function compatible with Estimator. The metric function itself takes in predictions, labels, and weights to compute a scalar measure. The metric key is an enum over supported metric functions, described in Section 2.4. During evaluation, the library supports computing both weighted and unweighted metrics, for example weights defined in Section 2.6, which facilitates evaluation in the context of unbiased learning-to-rank. The code snippet below shows how to build metric function.

```python
def eval_metric_fns():
    metric_fns = {
        "metric/ndcg@5": tfr.metrics.make_ranking_metric_fn(
            tfr.metrics.RankingMetricKey.NDCG, topn=5)
    }
    return metric_fns
```

### 4.6 Ranking Head

In the Estimator workflow, the Head API is an abstraction that encapsulates losses and metrics: Given a pair of Estimator-compatible loss function and metric function along with scores from a neural network, Head computes the values of the loss and metric and produces model predictions as output. The library provides a Ranking Head: a Head object with built-in support for ranking losses built in Section 4.4 and ranking metrics of Section 4.5. The signature of Ranking Head is shown below.

```python
def ranking_head = tfr.head.create_ranking_head(
    loss_fn=tfr.losses.make_loss_fn(_LOSS),
    eval_metric_fns=eval_metric_fns(),
    train_op_fn=train_op_fn)
```

### 4.7 Model Builder

A model builder, model_fn, is what puts all the different pieces together: scoring function, transform function, losses and metrics via ranking head. Recall that the model_fn returns operations related to predictions, metrics, and loss optimization. The output of model_fn and the graph constructed depends on the mode TRAIN, EVAL, or PREDICT. These are all handled internally by the library through make_groupwise_ranking_fn. The signature of a model builder, along with the overall flow to build a ranking Estimator is shown in Figure 1. The components of the ranking library can be used to construct a ranking model in several ways. The built-in model builder, make_groupwise_ranking_fn, provides a ranking model with multivariate scoring function and configurable losses and metrics. The user can also define a custom model builder which can use components from the library, such as losses or metrics.
Ranking models have a crucial training-serving discrepancy. During training the model receives a list of items, but during serving, it could potentially receive independent items which are generated by a separate retrieval algorithm. The ranking model builder handles this by generating a graph compatible with serving requirements and exporting it as a SavedModel [33]; a language agnostic object that can be loaded by the serving code, which can be in any low-level language such as C++ or Java.

5 USE CASES

Tensorflow Ranking is already deployed in several production systems at Google. In this section, we demonstrate the effectiveness of our library for two real-world ranking scenarios: Gmail search [40, 47] and document recommendation in Google Drive [38]. In both cases the model is trained on large quantities of click data that is beyond the capabilities of existing open source learning-to-rank packages, e.g., RankLib. In addition, in the Gmail setting, our model contains sparse textual features that cannot be naturally handled by the existing learning-to-rank packages.

5.1 Gmail Search

In one set of experiments, we evaluate several ranking models trained on search logs from Gmail. In this service, when a user types a query into the search box, five results are shown and user clicks (if any) are recorded and later used as relevance labels. To preserve user privacy, we remove personal information and anonymize data using k-anonymization. We obtain a set of features that consists of both dense and sparse features. Sparse features include word- and character-level n-grams derived from queries and email subjects. The vocabulary of n-grams is pruned to retain only n-grams that occur across more than k users. This is done to preserve user privacy, as well as to promote a common vocabulary for learning a shared representation across users. In total, we collect about 250M queries and isolate 10% of those to construct an evaluation set. Losses and metrics are weighted by Inverse Propensity Weighting [40] computed to counter position bias.

5.2 Document Recommendation in Drive

Quick Access in Google Drive [38] is a zero-state recommendation engine that surfaces documents currently relevant to the user when she visits the Drive home screen. We evaluate several ranking models trained on user click data over these recommended results. The set of features consists of mostly dense features, as described in Tata et al. [38]. In total we collected about 30M instances and set aside 10% of the set for evaluation.

<table>
<thead>
<tr>
<th>Table 1: Model performance with various loss functions. ΔM denotes % improvement in metric M over the Sigmoid Cross Entropy baseline. Best performance per column is in bold.</th>
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</thead>
<tbody>
<tr>
<td>(a) Gmail Search</td>
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<td>Sigmoid Cross Entropy (Pointwise)</td>
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<td>Logistic Loss (Pairwise)</td>
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<td>Softmax Cross Entropy (Listwise)</td>
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<tr>
<td>(b) Quick Access</td>
</tr>
<tr>
<td>Sigmoid Cross Entropy (Pointwise)</td>
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<tr>
<td>Logistic Loss (Pairwise)</td>
</tr>
<tr>
<td>Softmax Cross Entropy (Listwise)</td>
</tr>
</tbody>
</table>

5.3 Model Effectiveness

5.3.1 Setup and Evaluation. We consider a simple 3-layer feed-forward neural network with ReLU [32] non-linear activation units and dropout regularization [37]. We train models using pointwise, pairwise, and listwise losses defined in Section 2.5, and use Adagrad [15] to optimize the objective. We set the learning rate to 0.1 for Quick Access, and 0.3 for Gmail Search. The models are evaluated using the metrics defined in Section 2.4. Due to the proprietary nature of the models, we only report relative improvements with respect to a given baseline. Due to the large size of the evaluation datasets, all the reported improvements are statistically significant.

5.3.2 Effect of listwise losses. Table 1 summarizes the impact of different loss functions as measured by various ranking metrics for Gmail and Drive experiments respectively. We observe that a listwise loss performs better than a pairwise loss, which is in turn better than a pointwise loss. This observation confirms the importance of listwise losses for ranking problems over pairwise and pointwise losses, both in search and recommendation settings.

5.3.3 Incorporating sparse features. Unlike other approaches to learning to rank, like linear models, SVMs, or GBDTs, neural networks can effectively incorporate sparse features like query or document text. Neural networks handle sparse features by using embedding layers, which map each sparse value to a dense representation. These embedding matrices can be jointly trained along with the neural network parameters, allowing us to learn effective dense representations for sparse features in the context of a given task (e.g., search or recommendation). As prior work shows, these representations can substantially improve model effectiveness on large-scale collections [44].

To demonstrate this point, Table 2 reports the relative improvements from using sparse features in addition to dense features on Gmail Search. We use an embedding layer of size 20 for each sparse feature. We note that adding sparse features significantly boosts ranking quality across metrics and loss functions. This confirms the importance of sparse textual features in large-scale applications, and the effectiveness of TensorFlow Ranking in employing these features.
5.4 Distributed Training

Distributed training is crucial for applications of learning-to-rank to large scale datasets. Models built using the Estimator class allow for easy switching between local and distributed training, without changing the core functionality of the model. This is achieved via the Experiment class [12] given a distribution strategy.

Distributed training using TensorFlow consists of a number of worker tasks and parameter servers. We investigate the scalability of the model built for Gmail Search, the larger of our two datasets. We examine the effect of increasing the number of workers on the training speed. For the distributed strategy, we use between-graph replication, where each worker replicates the graph on a different subset of the data, and asynchronous training, where the gradients from different workers are asynchronously collected to update the gradients for the model.

For each of the following experiments, the number of workers ranges between 1 and 200, while the number of training epochs is fixed at 20 million. For robustness, each configuration is run 5 times, and the 95% confidence intervals are plotted.

5.4.1 Effect of scaling on training speed. We look at the impact of increasing the number of workers on the training speed in Figure 2. We measure training speed by the number of training steps executed per second. Due to the proprietary nature of the data, we report training speed normalized by the average training speed for one worker. The training scales up linearly in the initial phase, however when the pool of workers becomes too large, we are faced with two confounding factors. First is the communication overhead for gradient updates. Second, more workers stay idle waiting for data to become available. Therefore, the I/O costs begin to dominate, and the total training time stagnates and even slows down, as seen in the 20+ worker region of Figure 2.

Table 2: Model performance with dense and sparse textual features. \( \Delta M \) denotes % improvement in metric \( M \) over the corresponding baseline, when only dense features are used.

<table>
<thead>
<tr>
<th></th>
<th>AMRR</th>
<th>( \Delta )ARP</th>
<th>( \Delta )NDCG</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sigmoid Cross Entropy (Pointwise)</td>
<td>+6.06</td>
<td>+6.87</td>
<td>+3.92</td>
</tr>
<tr>
<td>Logistic Loss (Pairwise)</td>
<td>+5.40</td>
<td>+6.25</td>
<td>+3.51</td>
</tr>
<tr>
<td>Softmax Cross Entropy (Listwise)</td>
<td>+5.69</td>
<td>+6.25</td>
<td>+3.70</td>
</tr>
</tbody>
</table>

Figure 2: Normalized training speed for Gmail Search as a function of number of workers.

5.4.2 Effect of scaling on metrics. In Figure 3, we examine the impact of increasing the number of workers on weighted MRR. Due to the proprietary nature of the data, we report the metric value normalized by the average metric for one worker.

We observe that scaling does not generally have a significant impact on MRR, with two exceptions: using (a) a single worker, and (b) a large worker pool. We believe that the former requires more training cycles to achieve a comparable MRR. In the latter setting, gradient updates aggregated from too many workers become inaccurate, sending the model in a direction that is not well-aligned with the true gradient. However, in both cases, the overall effect on MRR is very small (roughly 0.03%), demonstrating the robustness of scaling with respect to model performance.

6 CONCLUSION

In this paper we introduced TensorFlow Ranking—a scalable learning-to-rank library in TensorFlow. The library is highly configurable and has easy-to-use APIs for scoring mechanisms, loss functions, and evaluation metrics. Unlike the existing learning-to-rank open source packages which are designed for small datasets, TensorFlow Ranking can be used to solve real-world, large-scale ranking problems with hundreds of millions of training examples, and scales well to large clusters. TensorFlow Ranking is already deployed in several production systems at Google, and in this paper we empirically demonstrate its effectiveness for Gmail search and Quick Access in Google Drive [38]. Our experiments show that TensorFlow Ranking can (a) leverage listwise loss functions, (b) effectively incorporate sparse features through embeddings, and (c) scale up without a significant drop in metrics. TensorFlow Ranking is available to the open source community, and we hope that it facilitates further academic research and industrial applications.

7 ACKNOWLEDGEMENTS

We thank the members of the TensorFlow team for their advice and support: Alexandre Passos, Mustafa Isip, Karmel Allison, Martin Wicke, Clemens Mewald and others. We extend our special thanks to our collaborators, interns and early adopters: Suming Chen, Zhen Qin, Chirag Sethi, Maryam Karimzadehgan, Makoto Uchida, Yan Zhu, Qingyao Ai, Brandon Tran, Donald Metzler, Mike Colagrosso, Patrick McGregor and many others at Google who helped in evaluating and testing the early versions of TF-Ranking.